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| Task. No.: | 3 | Points: | 5 | Easy start up |

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| Objectives:  1. Automatically load a default program when the robot has powered up. 2. Make the robot auto-initialize and auto-start-program after starting up. 3. Introduce relative waypoints. |

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| Description: This exercise aims to save time by initializing the robot automatically before starting pick and place program from previous exercise. |

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| Step | Action |
| 1 | Insert a *BeforeStart Sequence* which moves the robot to an initial position. Test it. |
| 2 | Modify the initial position to be *Relative* waypoint. Test it and compare behavior. |
| 3 | In the *BeforeStart Sequence* check that the gripper is open, and if not, open it. |
| 4 | In the *BeforeStart Sequence* popup the prompts the operator to confirm program run. |
| 5 | Select your pick and place program as the default program. |
| 6 | Configure the robot to auto initialize. |
| 7 | Configure the robot to auto start the default program. |
| 8 | Restart and verify that the program starts executing without any manual operation. |

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